

# Digital Manufacturing and Performance Testing for Application Specific Electronic Packaging (ASEP)

***i*MAPS New England 43rd Symposium & Expo**  
May 03, 2016

# Introduction

## Why do material choices and tight controls matter?



Because we need to move beyond fascinating toys (much less fascinating now) and move to real products.



<http://3dprint.com/24522/ge-pennsylvania-printing-3d/>

Move from real products that are really hard to make, but one single material and one single function.... to multi-material, multi-function.

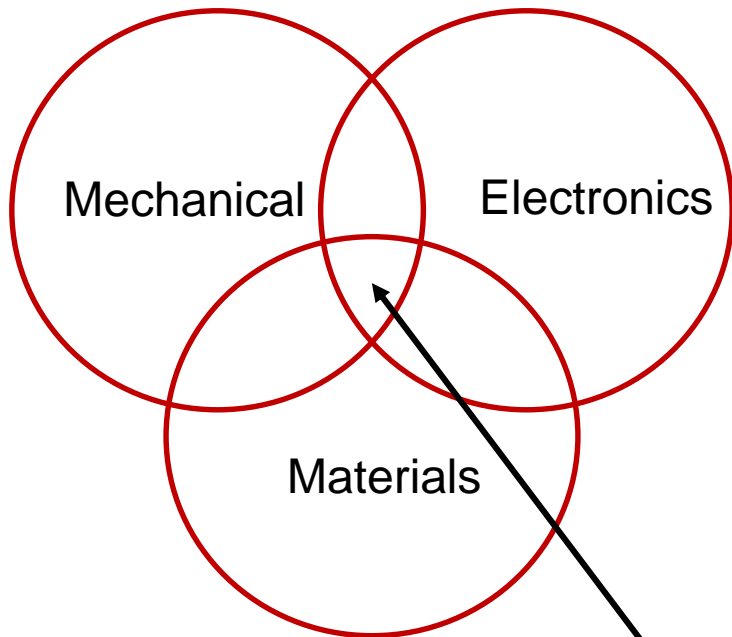


<http://www.neoglobeconsulting.com/blog/2014/5/31/whats-next-five-innovations-of-future-smartphones>

# Introduction

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## Structure + Electronics = Structural Defects



- Direct Digital Manufacturing (DDM) => Do we need it?
- Printed Circuit Structures (PCS) => What is it?
- What needs to be done next?
- Conclude

***Printed Circuit Structures*** ⇔ ***Structural Electronics***

# Direct Digital Manufacturing

Devices => SmartPump™ also know as micro-dispensing with pico-liter control, nFD™ also known as Fused Filament Fabrication with 12.5 micron features, nMill™ for precision milling and polishing and nPnP™ for pick and place. Diverse material placement for diverse material properties



SmartPump™



nFD™



nMill™



nPnP™

Slim profiles to allow all devices to set next to each other for tool swapping.

# Direct Digital Manufacturing

In Situ Processing => Heaters for the base plate or the pumps, photonic curing utilizing the Novacentrix PulseForge™, UV curing using arrays of UV diodes and diverse lasers for heating, curing, sintering, melting, cutting and surface treatment. These are standard processes in conventional



Heater  
Controller



PulseForge  
™



UV Cure

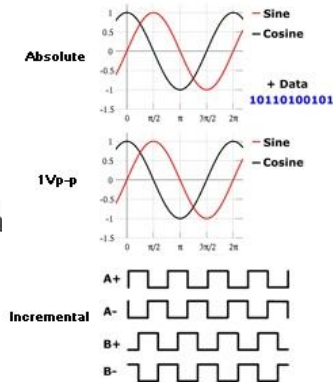


Lasers

All of these are options that fit on existing tool plates, thus combining all processes on a single platform.

# Direct Digital Manufacturing

In Situ Feedback => Precision in motion control using linear motors, but also utilizing encoder feedback for precise location of each device, Z height sensing and line scanning using precision Keyence sensors, Cognex vision for quantitative optical feedback and temperature



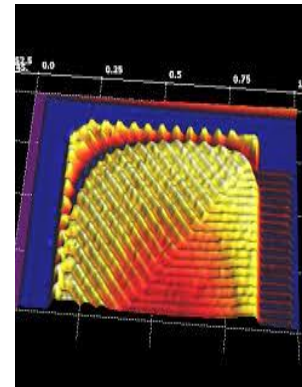
Encoder Feedback



Z Height Sensing Scanning



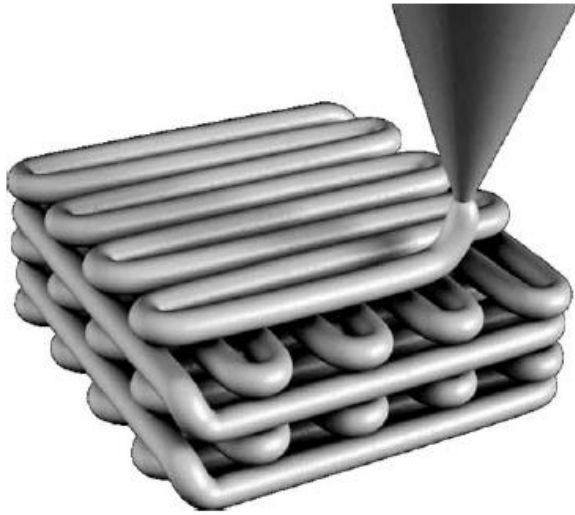
Vision



Temperature Feedback

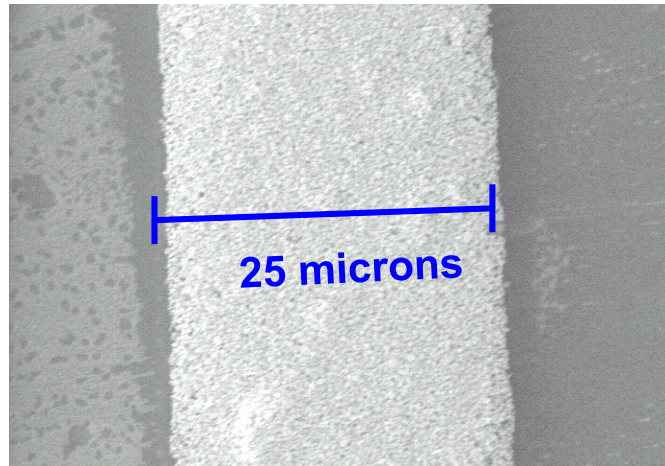
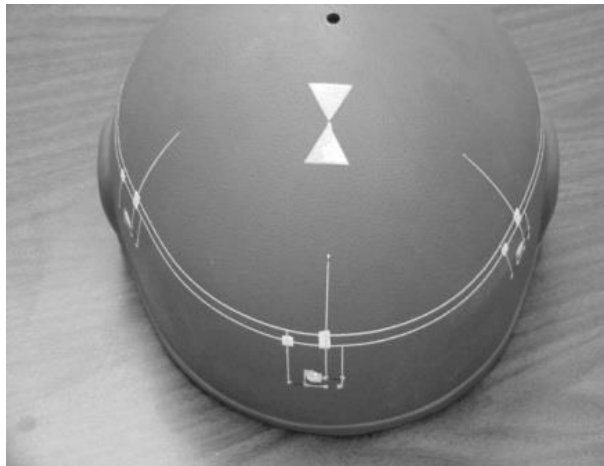
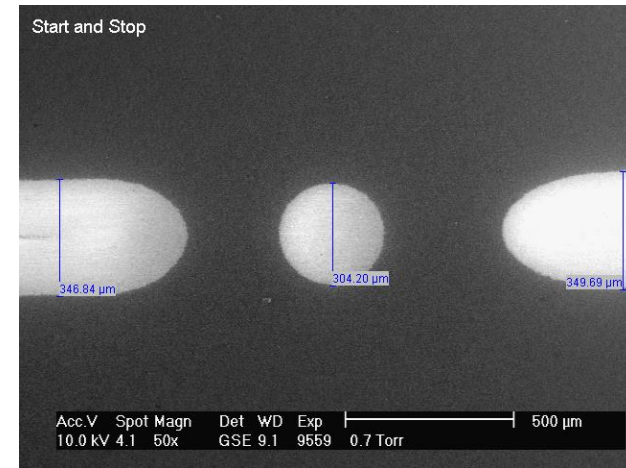
All of these are options that fit on existing tool plates, thus combining all processes on a single platform.

# Dispensing Material Control



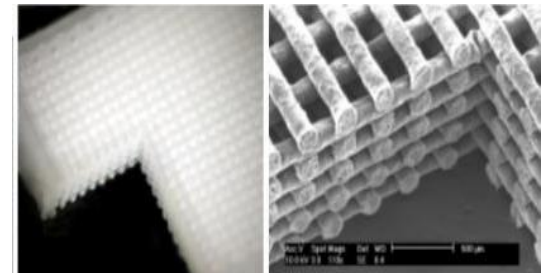
**Controlling: 1) Line Width, 2) Start/Stop, 3) Volume, 4) Juxtaposition in XYZ, and 5) Texture**

**Adjusting the “knobs” of valve opening, pressure, speed, gap and z movement, it is possible to control 3D prints.**



# Printing in 3D with Thermoplastics and More

- Thermoplastic materials (ABS, ULTEM™ ...) have been utilized in products for many years. 3D printing of those materials is not new. Advances in 3D software, temperature controls and motion control have enabled 3D printing.
- Thermoset materials are also in numerous products. Polymer (epoxy) can be loaded with a number of materials and including carbon fiber and then printed in a through nozzle system at room temperature; no clean room required.
- Not all polymers are well suited for 3D printing. Using thixotropic polymers with very high viscosities (greater than 100,000 cP), structures can be built by layering of material; “any” 3D shape.
- Strength of a polymer can be increased by mixing milled carbon fibers or carbon nanotubes into it; both demonstrate strength increases. Continuous carbon fiber is now part of this.
- Compatible printing with other materials to provide true composite builds and including metals.





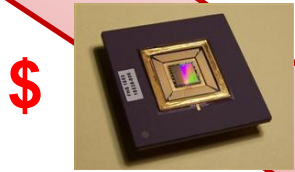
# ***Application Specific Electronic Packaging (ASEP)***

# A Hierarchy of System Packaging



Bare Die

*Package of Packages*



Packaged Die



Packaged Final System



Packaged Circuit Board Sub Assembly

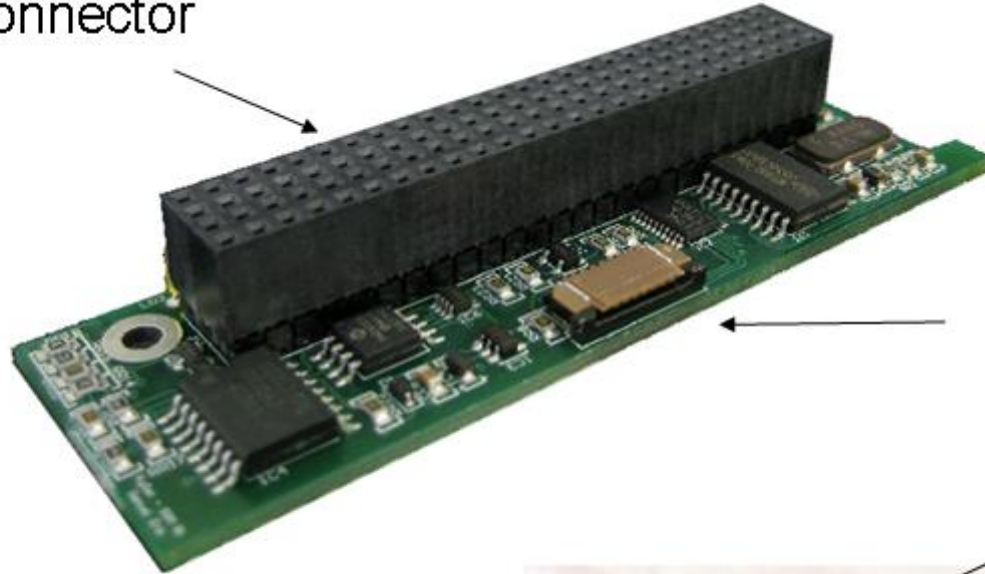


Packaged Chassis Assembly



Packaged Rack Assembly

Connector



Electronics

System Support Module



Hardware Fasteners

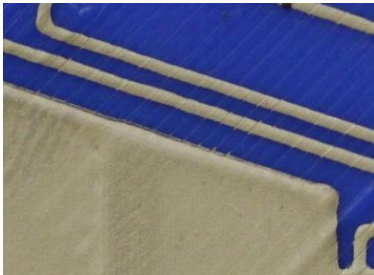
Electronics

Power System module

Connectors

**Most Significant Advantage:  
One system with multiple pumps for multiple results.**

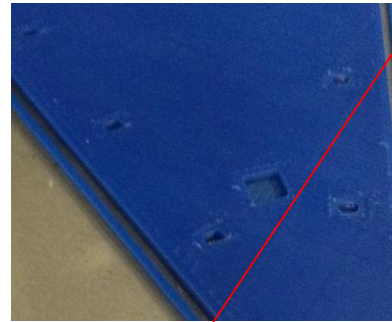
Printed Metal  
Conductors



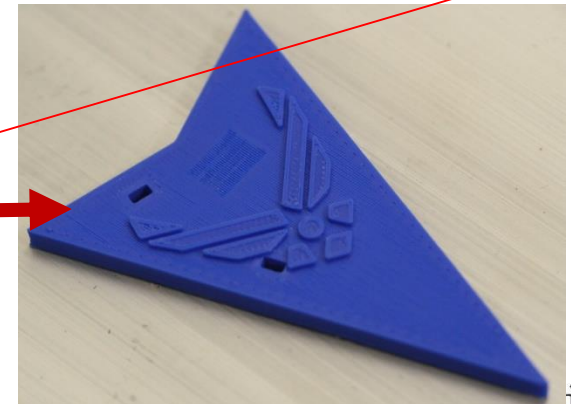
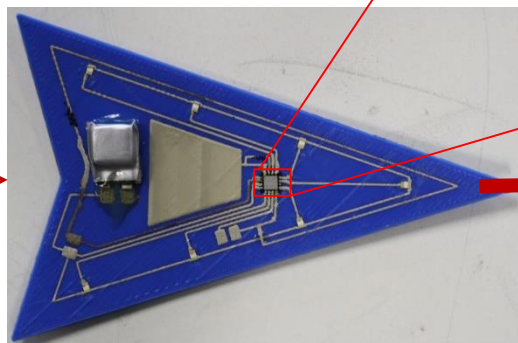
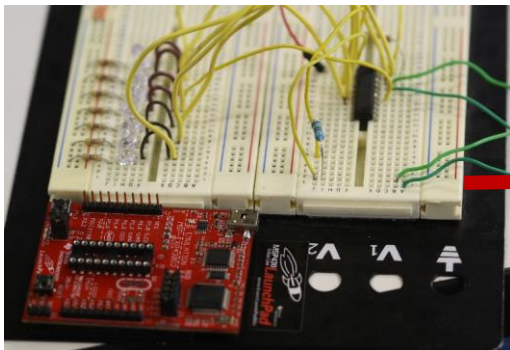
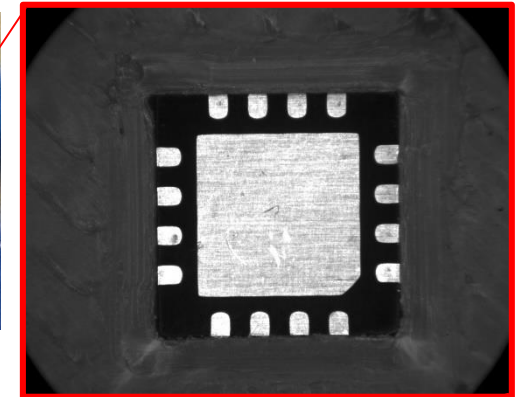
Printed



Plastic -



Pick and Place



# What is 3D Electronic Packaging

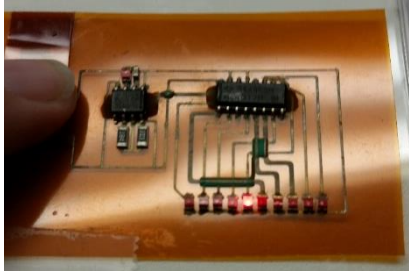
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© izmocar



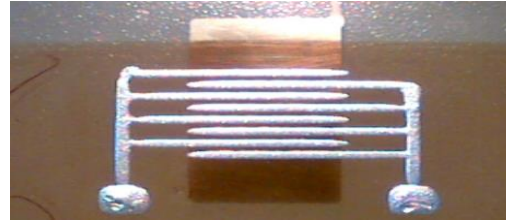
# Printed Electronics =>



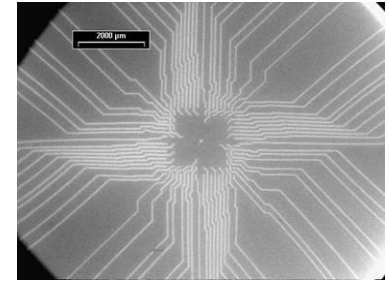
Flexible timing circuit



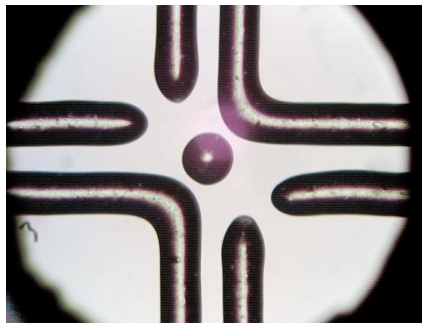
Passives



Polymer FETS



Breakout patterns



Adhesives

Borrowing from the Printed Electronics Industry....3D Printing is very similar. Both are layering approaches. Both use a variety of materials. Both are digital. Combining is a natural....what's not natural are the experts. The experts do not closely work together. They speak different languages.



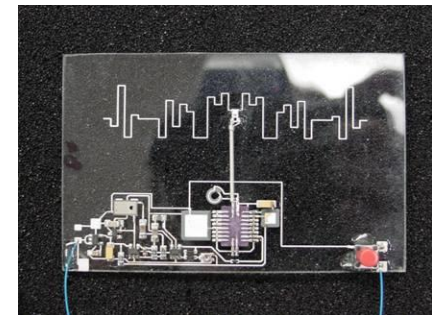
Antennas



Solder and vias

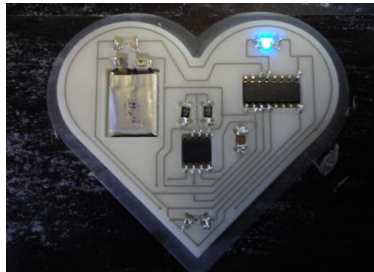


Electroluminescence

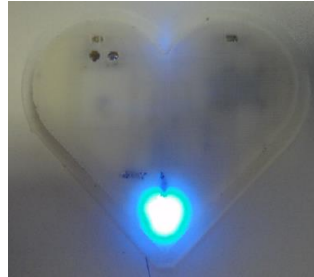


Working Devices

# 3D Printed Electronics =>



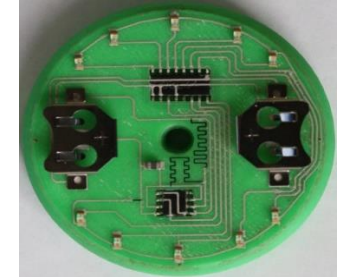
Timing circuit heart



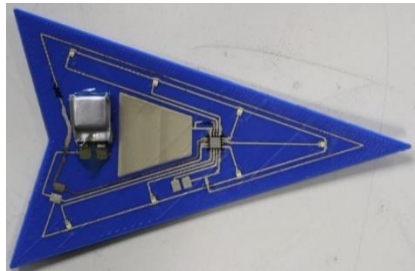
Timing circuit buried



CAD timing circuit puck

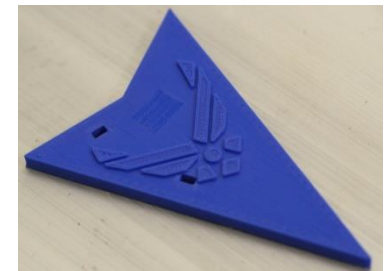


Timing circuit puck

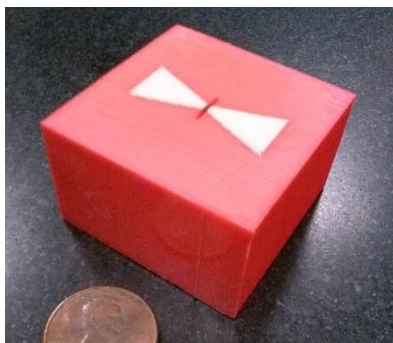


Micro-controller

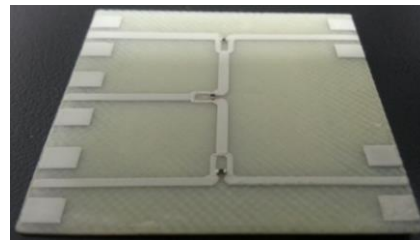
These devices are 3D printed or more completely described as fully digitally manufactured. Substrates for electronics are now structures. Structures for mechanical strength are now electrical substrates. It is critical to compete against State of the Art as a base foundation. This will lead to possibilities only Hollywood has.



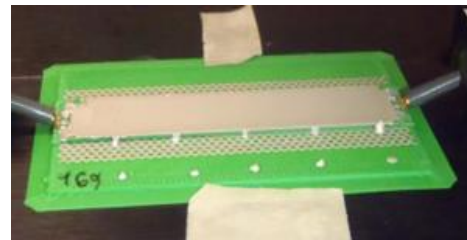
Buried micro-controller



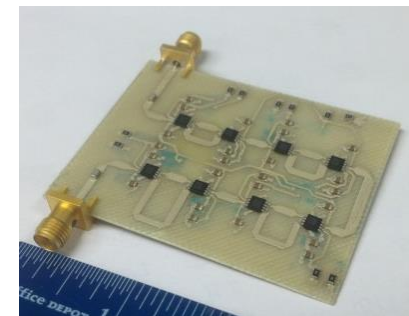
Antenna



Mult-GHz Power Divider

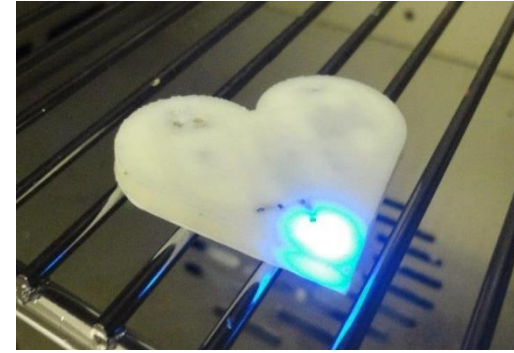
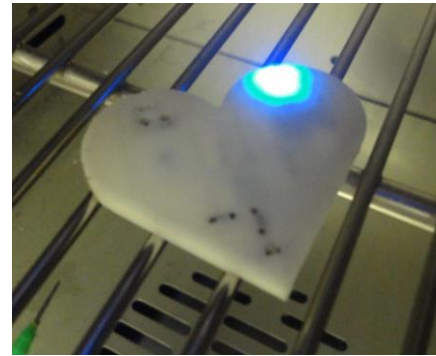
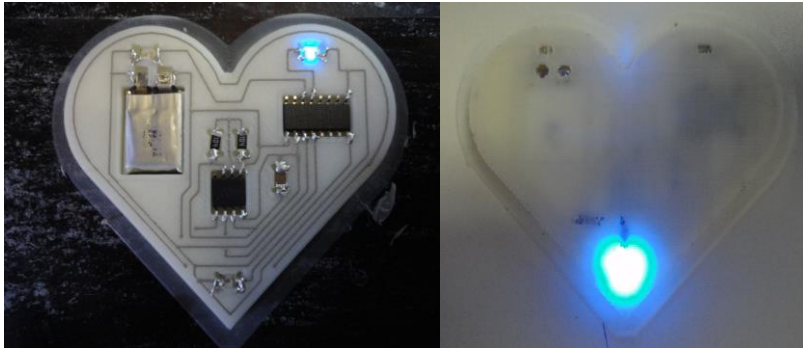


Stripline



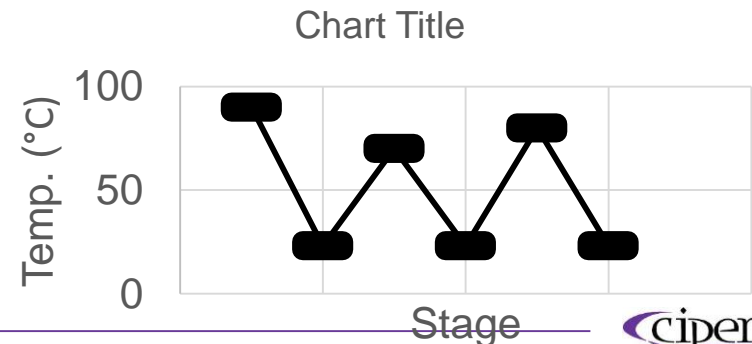
4 Bit Phase Shifter

# Printed Circuit Structure Temperature Cycling



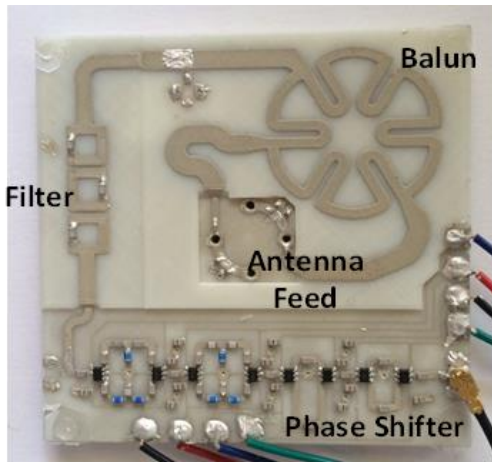
- Digital Patterning (Shape Agnostic)
- Multi-material (Multiple Properties)
- Print to Actives (nPnP)
- Single Tool (One tool, multiple processes)
- TLC (Graduate Students)
- Print and Play (Started Working during Printing)
- Nonstop Operation (Has been running more than 12 months nonstop)
- Temperature Cycling (Initial testing shows good results)

Action	Temp. (°C)	Baking (hrs)	Time	Status
Manufacture	90	4		Working
Oven post-print bake	90	2		Working
Standard Operation	23		130 days	Working
Thermal cycle	70	24		Working
Standard Operation	23		2 days	Working
Thermal cycle	80	8		Working
Standard Operation	23		50 days	Working
Present time	23			Working

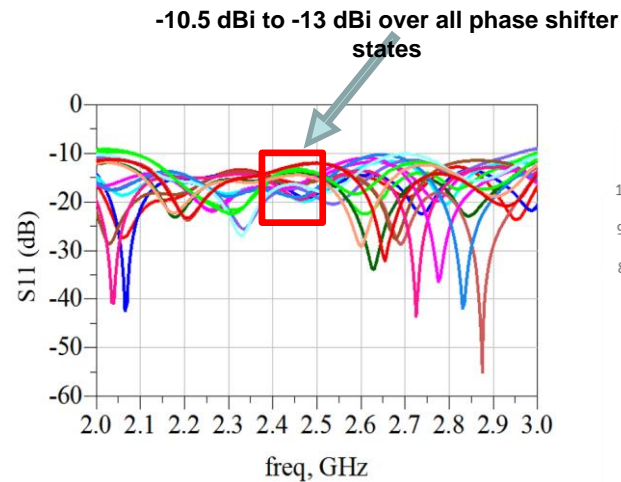




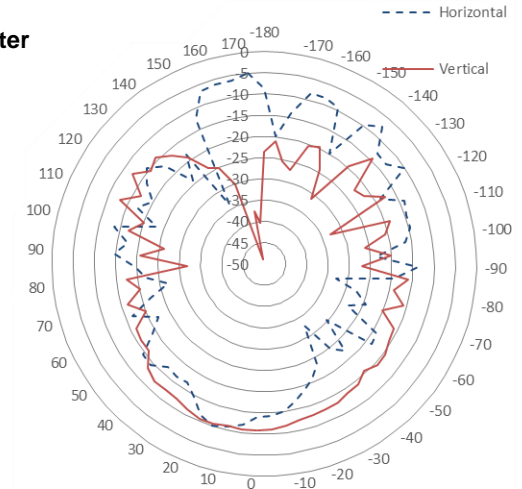
# PAA Unit Cell Results



Printed and populated unit cell



Unit cell return loss at all phases

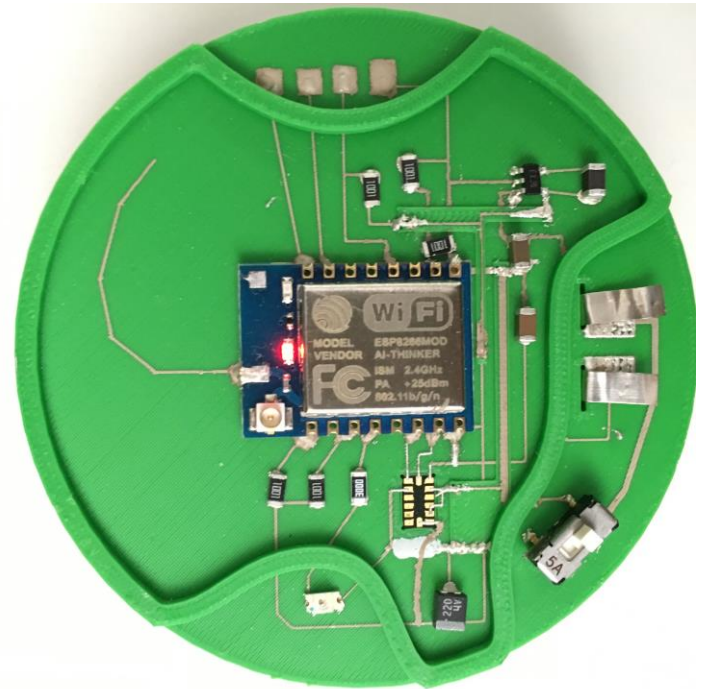
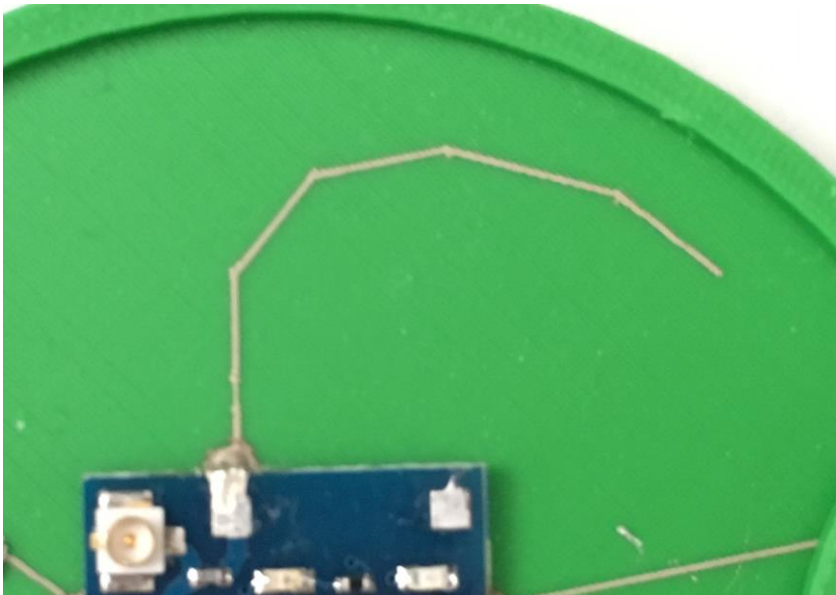


Antenna radiation pattern

# Wireless Shock Sensor

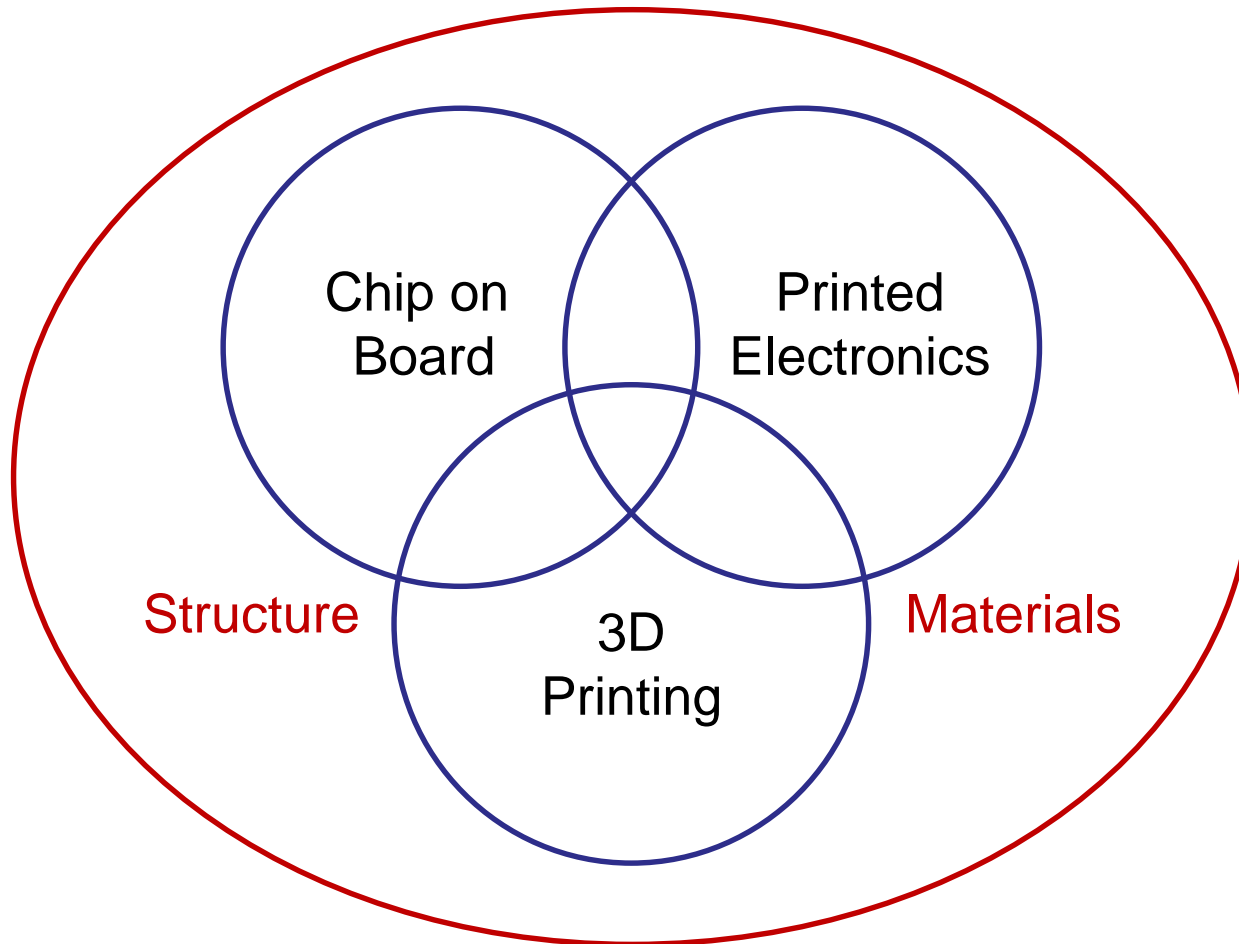
## Basic Design

Uses ESP8266 WiFi controller  
Powered by embedded 200 mAh Li-Po  
battery  
Printed antenna



The printed antenna is a simple curved monopole. Its range is about equal to the ceramic chip antenna it replaced.

## *Application Specific Electronic Packaging*



# Relevant Test standards

## ASEP

IPC

JEDEC

ISO

ASTM

DOD

IPC-MC-790  
(MCM)

JESD93  
(Hybrid/MCM)

ISO/TC 261

F42

MIL-PRF-  
38534

MCM - Multichip Modules

JOINT - Additive Manufacturing

\* IPC/JPCA-  
2291

ISO 9000

F-1578 thru  
F3152

Mil-STD-883

- Printed Electronics

- Printed Electronics
- Membrane Switches

MIL-HDBK-  
217

\* Joint w/ Japan Electronics Packaging  
Circuits Association

## IPC-SM-784 Guidelines for Chip-on-Board Technology Implementation

<http://www.ipc.org/TOC/IPC-SM-784.pdf>

### COB has two major subsets:

- Chip-and-Wire technology where the integrated circuit die is first adhesively bonded to a printed wiring board and is then interconnected by wire bonding with either gold or aluminum wire; and
- Flip Chip technology where the integrated circuit die is plated with solder bumps at the interconnect points and soldered in an inverted fashion to the board, thus effecting both attachment and interconnection in one step. **Flip chip bonding has also been done using a conductive organic-based adhesive (rather than solder) onto organic based printed boards**

<http://www.ipc.org/ContentPage.aspx?pageid=Printed-Electronics-Initiative>

## MIL-PRF-38534J APPENDIX D

### GENERIC PERFORMANCE VERIFICATIONS FOR NON-HERMETIC DEVICE TECHNOLOGIES

#### D.1 SCOPE

D.1.1 Scope. This appendix is intended to be used by manufacturers in developing their baseline flow of processes, screens, and Periodic Inspections / Qualified Manufacturers List (PI/QML) for non-hermetic devices. This appendix provides an acceptable standard which will be used to verify the performance requirements of compliant non-hermetic devices. This appendix is a mandatory part of the specification. The information contained herein is intended for compliance. Manufacturers may demonstrate a test and inspection system that achieves at least the same level of quality as could be achieved by complying with this appendix. These standards may be used as is or as modified in accordance with 3.9.1. The test flow presented in this appendix may not be appropriate for all non-hermetic technologies. For these types of devices, this appendix should be used as a starting point in developing an appropriate test flow.

NOTE: Non-hermetic devices should be used with caution and in appropriate end item use environments. Refer to D.3.3 for non-hermetic requirements.

# Accelerated Test Methods

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## HAST

The **highly accelerated stress test** (HAST) method was invented by Nihal Sinnadurai while working as a Research Engineer at British Telecommunications Research Laboratories in 1968 in order to perform highly accelerated reliability testing of electronics components that are likely to encounter humid environments during normal (ambient) operation. The method uses the principle of a non-saturating autoclave designed and engineered with no moving parts, to deliver close temperature ( $<1^{\circ}\text{C}$ ) and humidity ( $<2\%$  [RH](#)) control and a high reliability of the stress equipment. Nihal Sinnadurai and his team carried out many millions of device hours of reliability stress testing in HAST chambers, and arrived at a clear correlation with a humidity exponent as the stress accelerating agent.

[https://en.wikipedia.org/wiki/Highly\\_accelerated\\_stress\\_test](https://en.wikipedia.org/wiki/Highly_accelerated_stress_test)

# Accelerated Test Methods

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## ***HALT***

A **highly accelerated life test (HALT)**, is a [stress testing methodology](#) for accelerating product [reliability](#). HALT testing is currently in use by most major manufacturing organizations to improve product reliability in a variety of industries, including electronics, computer, medical and military.

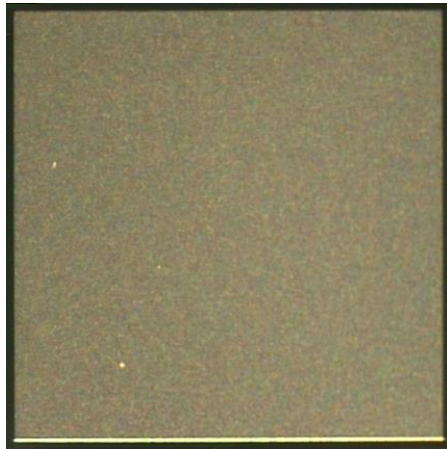
HALT can be effectively used multiple times over a product's life time. During product development, it can find design weakness when changes are much less costly to make. By finding weaknesses and making changes early, HALT can lower product development costs and compress time to market. When HALT is used at the time a product is being introduced into the market, it can expose problems caused by new manufacturing processes. When used after a product has been introduced into the market, HALT can be used to audit product reliability caused by changes in components, manufacturing processes or suppliers etc.

[https://en.wikipedia.org/wiki/Highly\\_accelerated\\_life\\_test](https://en.wikipedia.org/wiki/Highly_accelerated_life_test)



# Silicon Test Die

Die Attach Test Die



Silicon Dummy Test Die

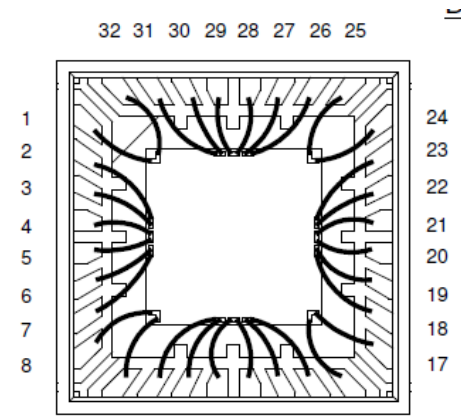
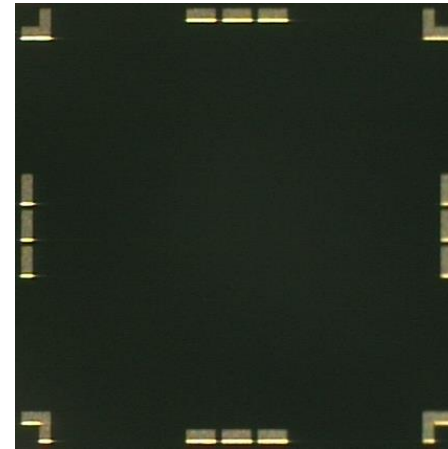
Size: 2.5mm x 2.5mm

Metallization;

Die Attach Pad – Au

Wire Bond Pad – Au

“Wire Bond” Test Die



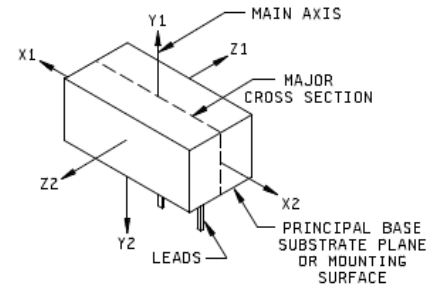
9 10 11 12 13 14 15 16  
QFN32W.5-DCW25322  
32L - 5X5mm

32 I/O Fan Out

# Mechanical Shock

## MS883 Test Method 2002.5 Mechanical Shock – Condition F

<u>Test condition</u>	<u>g level (peak)</u>	<u>Duration of pulse (ms)</u>
A	500	1.0
B	1,500	0.5
C	3,000	0.3
D	5,000	0.3
E	10,000	0.2
F	20,000	0.2
G	30,000	0.12



CAUTION: If this test is performed using a potting compound type test fixture (e.g., waterglass/sodium silicate) the facility performing the test shall assure that this procedure/material does not mask fine/gross leakers.

FIGURE 1a. Orientation of microelectronic device to direction of applied force.

**Orientations X1, X2, Y2, Y1, Z1, and Z2**

## METHOD 2005.2 VIBRATION FATIGUE

1. PURPOSE. The purpose of this test is to determine the effect on the device of vibration in the frequency range specified.
2. APPARATUS. Apparatus for this test shall include equipment capable of providing the sustained vibration within the specified levels and the necessary optical and electrical equipment to conduct post-test measurements.
3. PROCEDURE. The device shall be rigidly fastened on the vibration platform and the leads or cables adequately secured. The device shall be vibrated with a constant amplitude simple harmonic motion having a peak acceleration corresponding to the specified test condition. For test condition A, constant amplitude harmonic motion in the range of  $60 \pm 20$  Hz having an amplitude of 0.06 inch double amplitude (total excursion) shall be acceptable as an alternative to the specified peak acceleration. The vibration shall be applied for  $32 \pm 8$  hours minimum, in each of the orientations X, Y, and Z for a total of 96 hours, minimum. When specified, devices with an internal cavity containing parts or elements subject to possible movement or breakage during vibration shall be further examined by radiographic examination in accordance with method 2012 or by delidding or opening and internal visual examination at 30X magnification to reveal damage or dislocation. Where this test is performed as part of a group or subgroup of tests, the post-test measurements or inspections need not be performed specifically at the conclusion of this test, but may be performed once at the conclusion of the group or subgroup.

### Test condition Peak acceleration, g

A	20
B	50
C	70

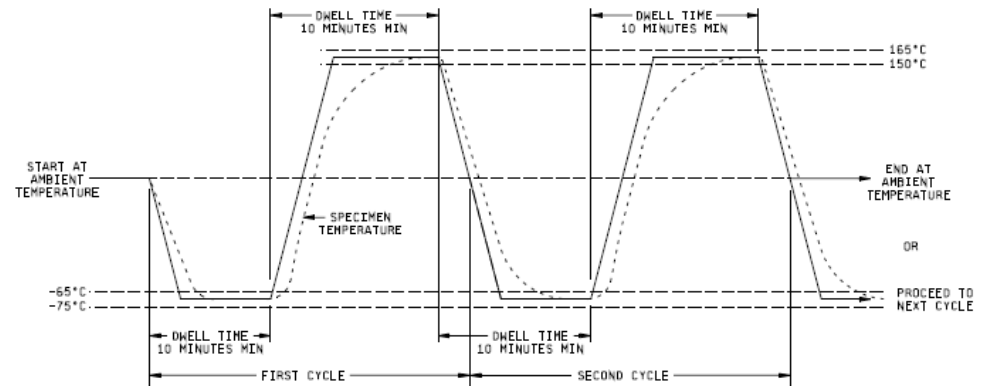
# Temperature Cycling

## MS883 Test Method 1010.8 Temperature Cycling – Condition A

TABLE I. Temperature-cycling test conditions.

Step	Minutes	Test condition temperature (°C)					
		A	B	C	D	E	F
1 Cold	≥10	-55 +0 -10	-55 +0 -10	-65 +0 -10	-65 +0 -10	-65 +0 -10	-65 +0 -10
2 Hot	≥10	85 +10 -0	125 +15 -0	150 +15 -0	200 +15 -0	300 +15 -0	175 +15 -0

NOTE: Steps 1 and 2 may be interchanged. The load temperature may exceed the + or - zero (0) tolerance during the recovery time. Other tolerances shall not be exceeded.



**10 Minute Dwell at extremes**

# ESD Testing – Package Level

## Performance Work Statement (SOW)

??

### MS883 Test Method 3015.9 ELECTROSTATIC DISCHARGE SENSITIVITY CLASSIFICATION

1. PURPOSE. This method establishes the procedure for classifying microcircuits according to their susceptibility to damage or degradation by exposure to electrostatic discharge (ESD). This classification is used to specify appropriate packaging and handling requirements in accordance with MIL-PRF-38535, and to provide classification data to meet the requirements of MIL-STD-1686.

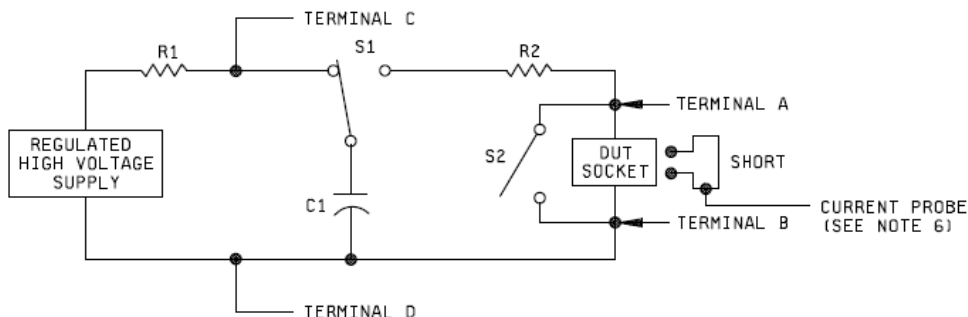


TABLE III. Device ESD failure threshold classification.

Class 0	< 250 volts
Class 1A	250 volts to 499 volts
Class 1B	500 volts to 999 volts
Class 1C	1,000 volts to 1,999 volts
Class 2	2,000 volts to 3,999 volts
Class 3A	4,000 volts to 7,999 volts
Class 3B	≥ 8,000 volts

## Classification Threshold

# Integrated Work-cell ESD Control & Monitoring System



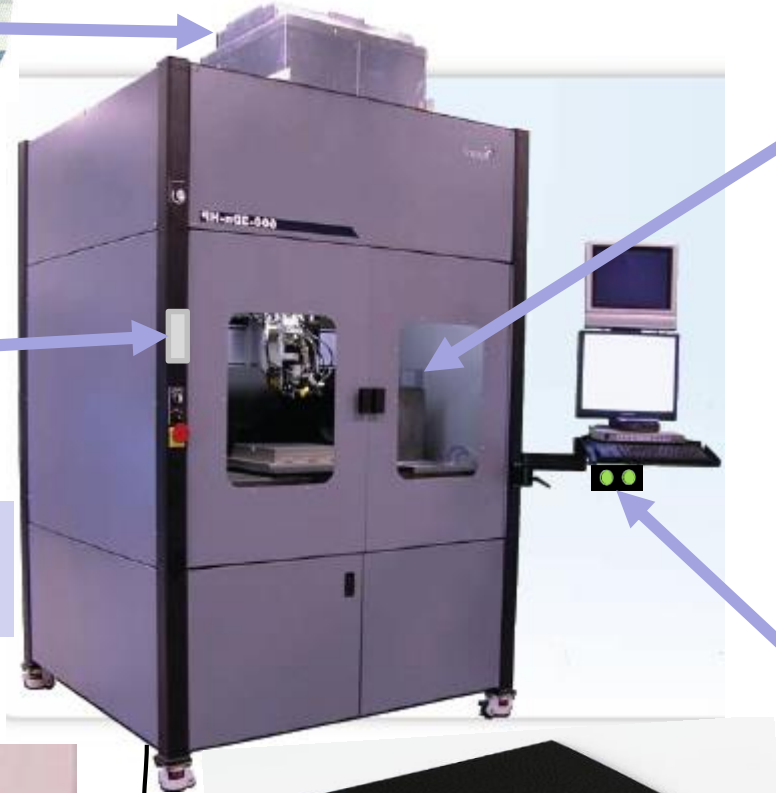
**Overhead Ionizer**



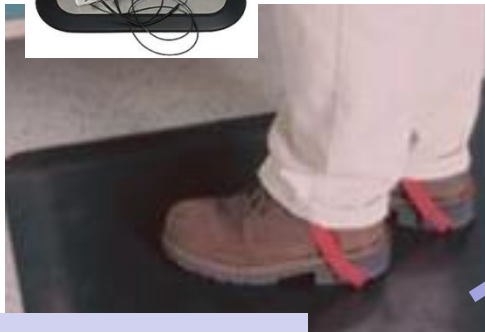
**Localized Ionizer**



**ESD Wrist/Shoe Strap Testers**



**ESD Wrist Strap**



**ESD Shoe Strap**

**ESD Floor Mat**

## State of the Art & What's Next =>

- FR4 – complex and very mature
- Ceramic (LTCC) – complex and very mature
- Multichip modules – complex and very mature
- Flexible electronics – building complexity and maturity
- Printed electronics – pushing to compete, and gaining ground
- 3D printed electronics – infancy
  - Demonstrations
  - Limited testing
  - DC to RF is very different

Hybrid approach – Print what you can, place what you can't... “get by with a little help from my friends.”

Mindset of 2.5D will not change if we cannot truly demonstrate 3D effectively, accurately and with significant speed.

RF needs a focus....wireless is not going away.

